

IN THE SPECIFICATION:

Delete page 10, lines 1-19 in its entirety and substitute the following:

– As shown in Fig. 1, in raised operating position the guy supports 12 are inclined not only in relation to luffing plane 13 but also in relation to the cross-sectional plane perpendicular to the longitudinal axis of the telescopic boom at angle β shown in Fig. 1. The inclination in relation to cross-sectional plane 15 is selected in such manner that resulting force F_{res} acting from a given guy cable 10 on the given guy support 12 has a lever arm against guy support 12, that is, guy support 12 does not run precisely in the working line of the resulting force F_{res} . As shown in Fig. 1, guy cable 10 runs out over guy support 12 and is turned around at its projecting end via a deflection roller 16. The working direction of the resulting force accords with the halving of the angle defined by the two cable segments of the guy cable running together at deflection roller 16. Guy support 10 is thus inclined slightly backward, i.e., inclined toward pivot section 2, so that guy cable 10 tries to press guy support 12 into its transportation position. The corresponding torque is however captured by the pertinent tension rod or stay 17, which on the one hand is pivoted to the pertinent guy support 12 and to the collar of the second telescopic section 6. The slight inclination of guy support 12 to the pivot section ensures that tension rod or stay 17 is always stressed only upon traction. As shown in Fig. 1, tension rod 17 consists of a telescopic pipe the length of which can be adjusted. The two pipe sections of tension rod 17 can be locked together in various extended positions in order to adjust the length of tension rod 17 to various extensions of the telescopic boom.--